



Mitchell Moore (ASM), Aaron Shwarts (AE)

### Problem Statement and Background

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- Automatic multivator height adjustment
- Installation of electronics on trailer
- Trailer ballasting

### Impact

- Revolutionize new technology in the agriculture industry
- Increase field potential to help farmers get more money into their pockets

### Environmental Factors

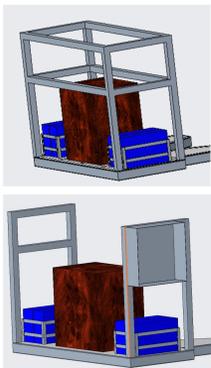
In consideration of today's growing issues with climate change, environmental pollution, and increased societal pressures to these issues The Purdue AgBOT seeks to:

- Limit application of pesticides onto crops by implementing precision application and mechanical destruction
- Monitor trouble areas of fields with geolocation tagging

### Constraints and Criteria

- \$5000 max project spending
- The current trailer frame shall be used for 2020 competition
- Current multivators actuators would be used for 2020 competition
- Three-point Hitch would be kept as this allows for changing implements
- Electronics and power equipment to be moved to trailer from UTV

### Alternative Solutions



- #1 Storage For Electronics On Trailer:
1. Solid Frame- Lots of storage, simple, roomy, blocks engine and containers
  2. Independent Frame- Engine access, electronics access, not as stable

## Title: AgBot-1

### Decision Making

- Design of sprayer tank mounts to utilize slimmer tanks
- Design of automatic depth control of dynamic ground changes though a field
- Design of electronic box brackets to allow trailer to be stand alone
- Pivoting electronic mounts too provides access to various equipment

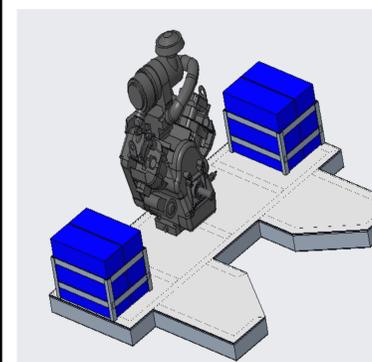
### Economic Analysis

- Estimated Cost of Metal: \$150
- Cost of Lidar Sensors: \$600
- Use of standard metal tubing reduced cost of materials
- Simple design for equipment rack reduced cost of fabrication in manhours

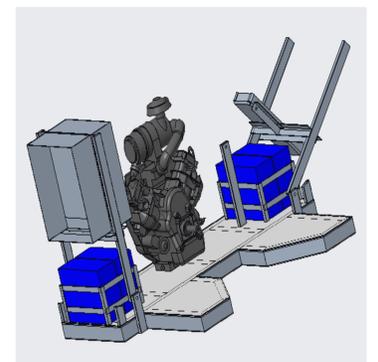
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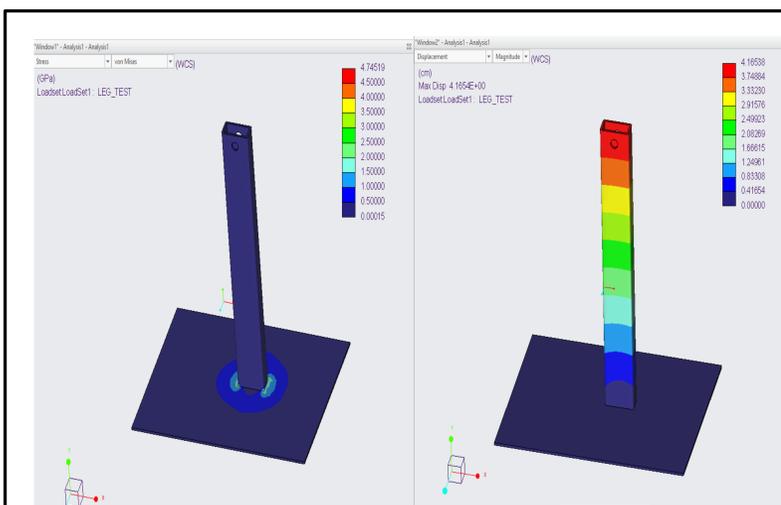
### New design



- All Computing on trailer
- Pivoting racks for access
- Racks locked with clevis pins
- Slim chemical containers
- Anti-sway 3-pt hitch
- Auto height control
- GPS on trailer



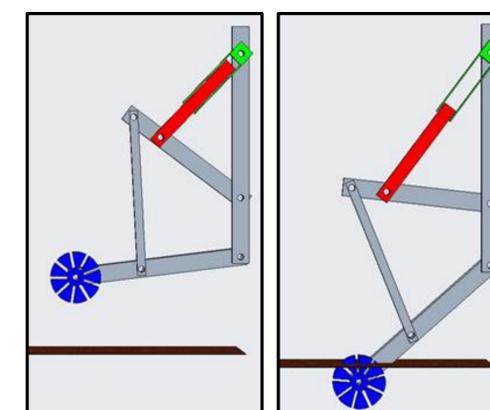
New configuration allows the system to be moved to any vehicle with a hitch.



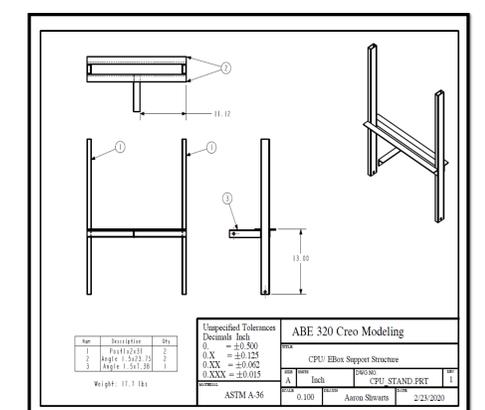
- Analysis of design to find stress concentrations performed in Creo using 500 lb loading on equipment racks.

### Process Implementation Plans

Multivator Simulation and Arduino Code for Auto Height Control



Full 3D Model and Drawings For Added Structural Component



- Testing Plan for determining Effectiveness of Height Control System

**Sponsor:**  
Roger Tormoehlen

**Technical Advisor:**  
Richard Fox

**Instructors:**  
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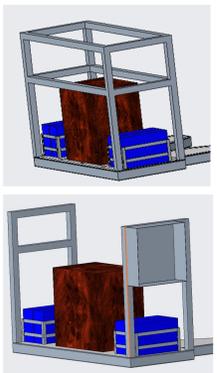
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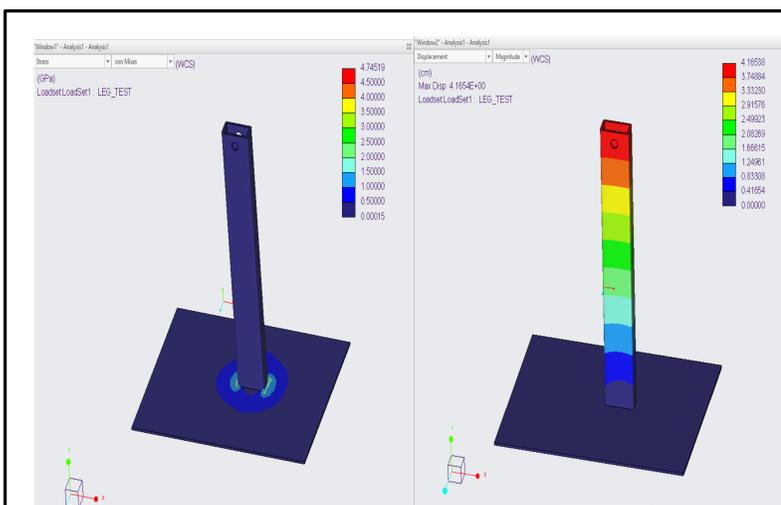
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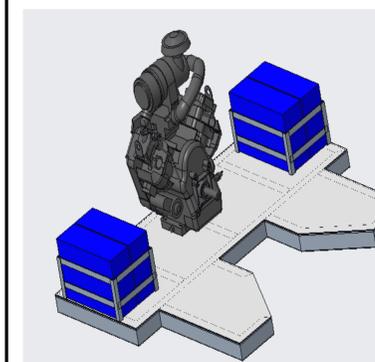


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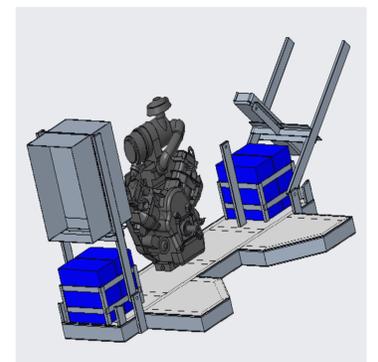
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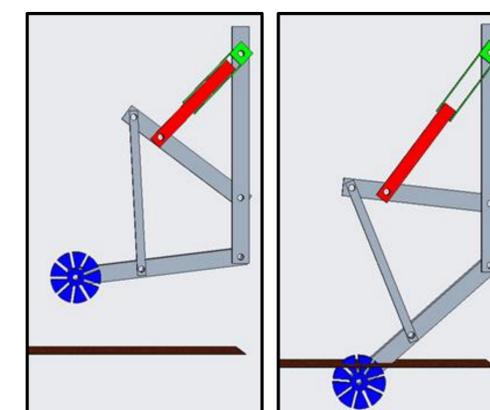
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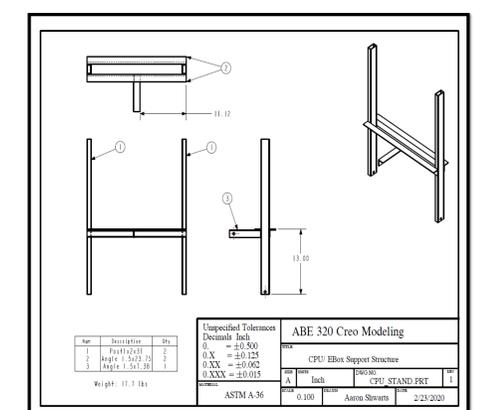
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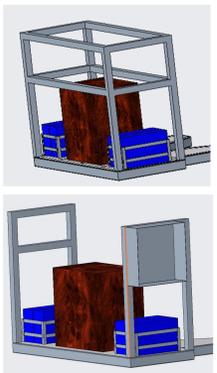
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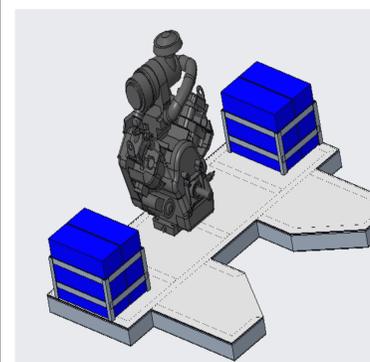
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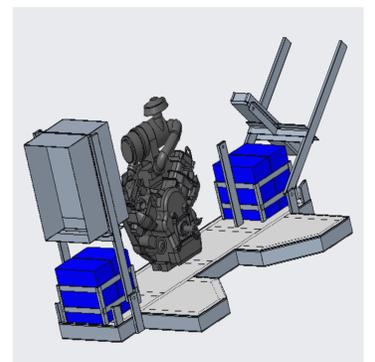
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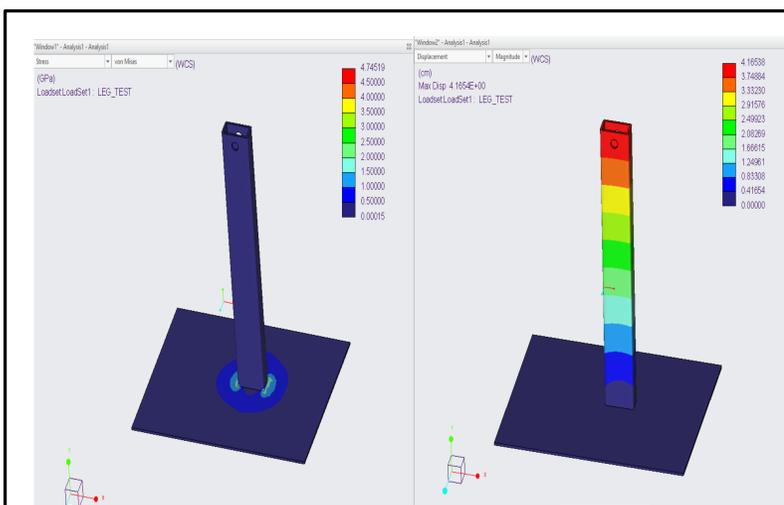
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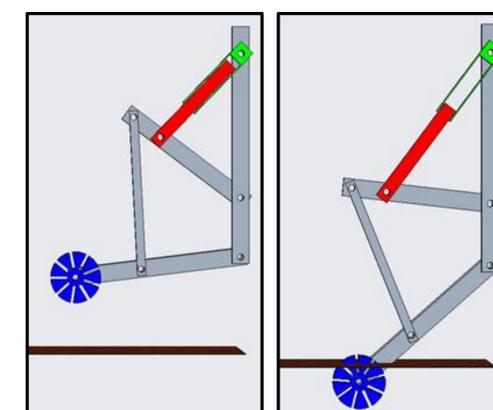
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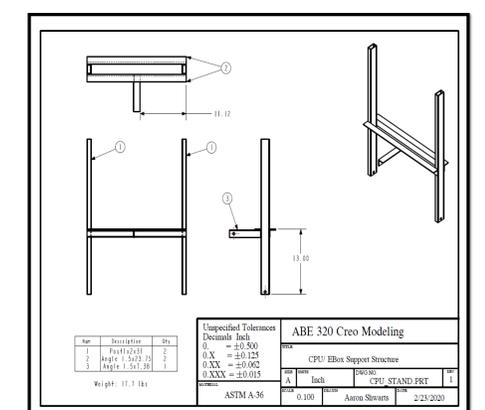
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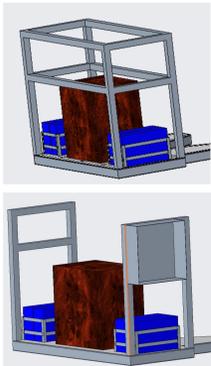
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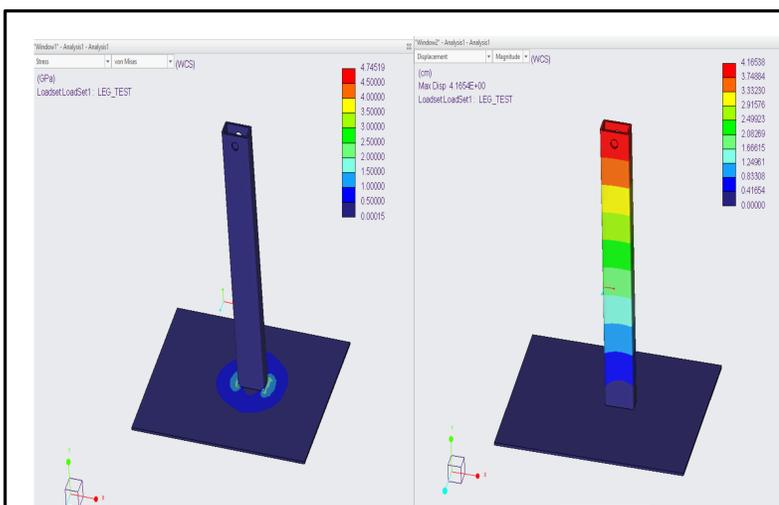
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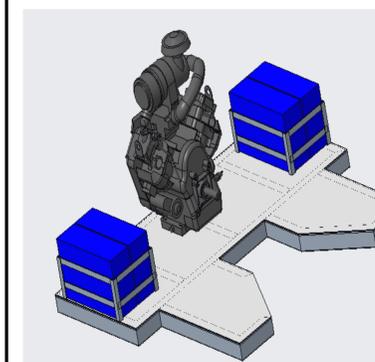


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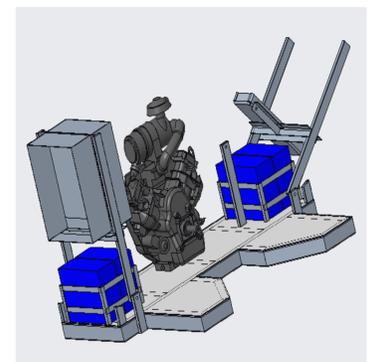
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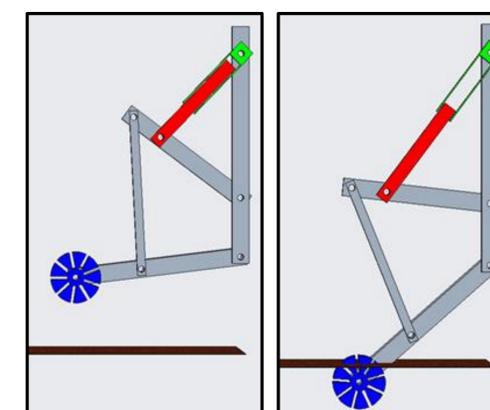
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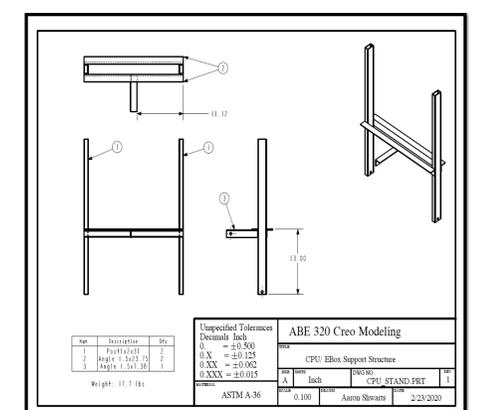
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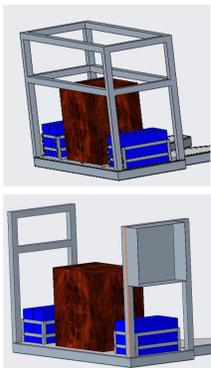
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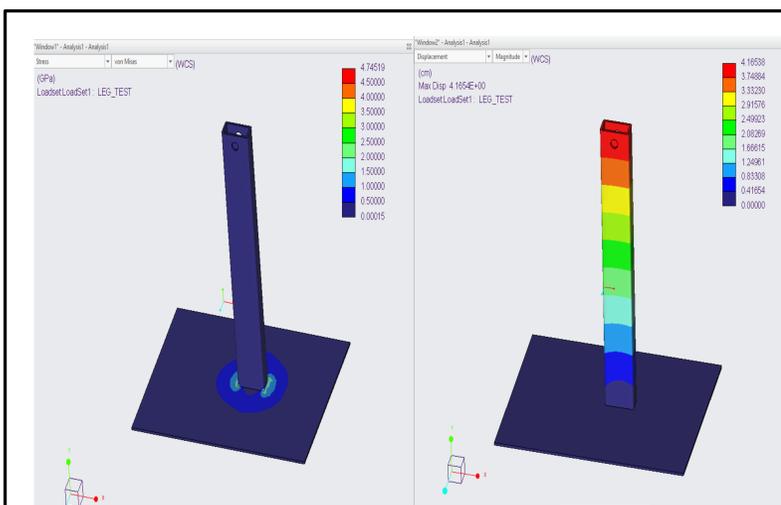
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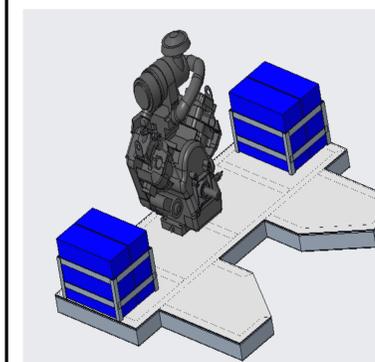


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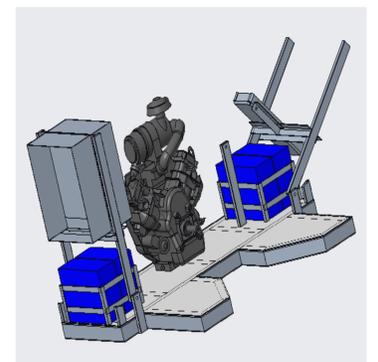
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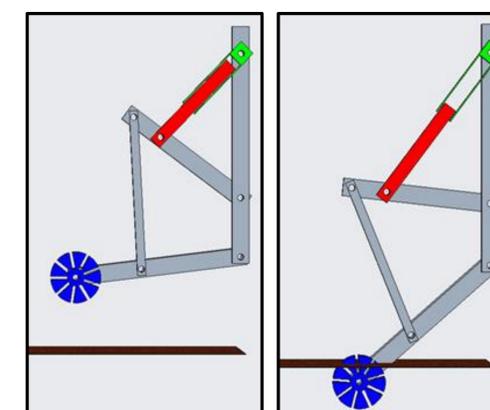
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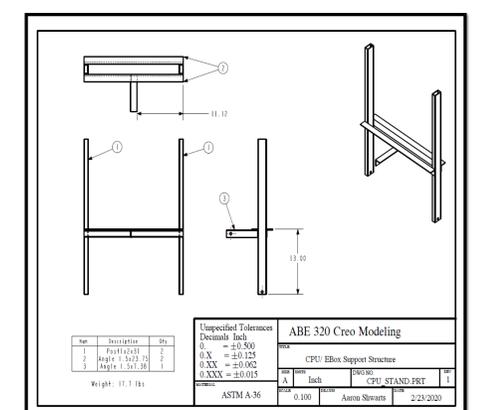
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